

Package ‘SLSEdesign’

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Title Optimal Regression Design under the Second-Order Least Squares Estimator

Version 0.0.5

Description With given inputs that include number of points, discrete design space, a measure of skewness, models and parameter value, this package calculates the objective value, optimal designs and plot the equivalence theory under A- and D-optimal criteria under the second-order Least squares estimator. This package is based on the paper ``Properties of optimal regression designs under the second-order least squares estimator'' by Chi-Kuang Yeh and Julie Zhou (2021) <[doi:10.1007/s00362-018-01076-6](https://doi.org/10.1007/s00362-018-01076-6)>.

URL <https://github.com/chikuang/SLSEdesign>

BugReports <https://github.com/chikuang/SLSEdesign/issues>

License GPL-3

Encoding UTF-8

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Imports CVXR

Suggests knitr, rmarkdown

VignetteBuilder knitr

NeedsCompilation no

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|-------------|--|
| Aopt | <i>Calculate the A-optimal design under the second-order Least squares estimator</i> |
|-------------|--|

Description

Calculate the A-optimal design under the second-order Least squares estimator

Usage

```
Aopt(N, u, tt, FUN, theta, num_iter = 1000)
```

Arguments

| | |
|----------|---|
| N | The number of sample points in the design space. |
| u | The discretized design space. |
| tt | The level of skewness between 0 to 1 (inclusive). When tt=0, it is equivalent to compute the A-optimal design under the ordinary least squares estimator. |
| FUN | The function to calculate the derivative of the given model. |
| theta | The parameter value of the model. |
| num_iter | Maximum number of iteration. |

Details

This function calculates the A-optimal design and the loss function under the A-optimality. The loss function under A-optimality is defined as the trace of the inverse of the Fisher information matrix

Value

A list that contains 1. Value of the objective function at solution. 2. Status. 3. Optimal design

Examples

```
poly3 <- function(xi, theta){
  matrix(c(1, xi, xi^2, xi^3), ncol = 1)
}
Npt <- 101
my_design <- Aopt(N = Npt, u = seq(-1, +1, length.out = Npt),
  tt = 0, FUN = poly3, theta = rep(0,4), num_iter = 2000)
round(my_design$design, 3)
my_design$val
```

calc_phi*Calculate the loss function of the A-, c- or D-optimal design*

Description

Calculate the loss function of the A-, c- or D-optimal design

Usage

```
calc_phi(  
  design,  
  theta,  
  FUN,  
  tt,  
  A,  
  criterion = "D",  
  cVec = rep(0, length(theta))  
)
```

Arguments

| | |
|-----------|---|
| design | The resulted design that contains the design points and the associated weights |
| theta | The parameter value of the model |
| FUN | The function to calculate the derivative of the given model. |
| tt | The level of skewness |
| A | The calculated covariance matrix |
| criterion | The criterion to be used for the design, either "D" for D-optimality or "A" for A-optimality. Default is "D". |
| cVec | c vector used to determine the combination of the parameters. This is only used in c-optimality |

Details

This function calculates the loss function of the design problem under the A- or D-optimality. The loss functions under A-, or D-optimality are defined as the trace and log determinant of the inverse of the Fisher information matrix

Value

The loss of the model at each design points

Examples

```
my_design <- data.frame(location = c(0, 180), weight = c(1/2, 1/2))
theta <- c(0.05, 0.5)
peleg <- function(xi, theta){
  deno <- (theta[1] + xi * theta[2])^2
  rbind(-xi/deno, -xi^2/deno)
}
A <- matrix(c(1, 0, 0, 0, 0.2116, 1.3116, 0, 1.3116, 15.462521), byrow = TRUE, ncol = 3)
res <- calc_phi(my_design, theta, peleg, 0, A, criterion = "A")
res
```

copt

Calculate the c-optimal design under the SLSE with the given combination of the parameters

Description

Calculate the c-optimal design under the SLSE with the given combination of the parameters

Usage

```
copt(N, u, tt, FUN, theta, num_iter = 1000, cVec)
```

Arguments

| | |
|----------|--|
| N | The number of sample points in the design space. |
| u | The discretized design space. |
| tt | The level of skewness. When tt=0, it is equivalent to compute the c-optimal design under the ordinary least squares estimator. |
| FUN | The function to calculate the derivative of the given model. |
| theta | The parameter value of the model. |
| num_iter | Maximum number of iteration. |
| cVec | c vector used to determine the combination of the parameters |

Details

This function calculates the c-optimal design and the loss function under the c-optimality. The loss function under c-optimality is defined as the log determinant of the inverse of the Fisher information matrix.

Value

A list that contains 1. Value of the objective function at solution. 2. Status. 3. Optimal design

Examples

```

poly3 <- function(xi, theta){
  matrix(c(1, xi, xi^2, xi^3), ncol = 1)
}
Npt <- 101
my_design <- copt(N = Npt, u = seq(-1, +1, length.out = Npt),
  tt = 0, FUN = poly3, theta = rep(0,4), num_iter = 2000,
  cVec = c(0,1,1,1))
round(my_design$design, 3)
my_design$val

```

Dopt

Calculate the D-optimal design under the SLSE

Description

Calculate the D-optimal design under the SLSE

Usage

```
Dopt(N, u, tt, FUN, theta, num_iter = 1000)
```

Arguments

| | |
|----------|--|
| N | The number of sample points in the design space. |
| u | The discretized design space. |
| tt | The level of skewness. When tt=0, it is equivalent to compute the D-optimal design under the ordinary least squares estimator. |
| FUN | The function to calculate the derivative of the given model. |
| theta | The parameter value of the model. |
| num_iter | Maximum number of iteration. |

Details

This function calculates the D-optimal design and the loss function under the D-optimality. The loss function under D-optimality is defined as the log determinant of the inverse of the Fisher information matrix.

Value

A list that contains 1. Value of the objective function at solution. 2. Status. 3. Optimal design

Examples

```

poly3 <- function(xi, theta){
  matrix(c(1, xi, xi^2, xi^3), ncol = 1)
}
Npt <- 101
my_design <- Dopt(N = Npt, u = seq(-1, +1, length.out = Npt),
  tt = 0, FUN = poly3, theta = rep(0,4), num_iter = 2000)
round(my_design$design, 3)
my_design$val

```

plot_dispersion *Verify the optimality condition for an optimal design (A-, c- or D-optimality)*

Description

Verify the optimality condition for an optimal design (A-, c- or D-optimality)

Usage

```

plot_dispersion(
  u,
  design,
  tt,
  FUN,
  theta,
  criterion = "D",
  cVec = rep(0, length(theta))
)

```

Arguments

| | |
|------------------|---|
| u | The discretized design points |
| design | The optimal design containing the design points and the associated weights |
| tt | The level of skewness |
| FUN | The function to calculate the derivative of the given model |
| theta | The parameter value of the model |
| criterion | The optimality criterion: one of "A", "c", or "D" |
| cVec | c vector used to determine the combination of the parameters. This is only used in c-optimality |

Details

This function visualizes the directional derivative under A-, c-, or D-optimality using the general equivalence theorem. For an optimal design, the directional derivative should not exceed the reference threshold

Value

A plot verifying the general equivalence condition for the specified optimal design

Examples

```

poly3 <- function(xi, theta){
  matrix(c(1, xi, xi^2, xi^3), ncol = 1)
}
design_A <- data.frame(location = c(-1, -0.464, 0.464, 1),
                       weight = c(0.151, 0.349, 0.349, 0.151))
design_D = data.frame(location = c(-1, -0.447, 0.447, 1),
                      weight = rep(0.25, 4))
u <- seq(-1, 1, length.out = 201)
par(mfrow = c(2,2))
plot_dispersion(u, design_A, tt = 0, FUN = poly3, theta = rep(0, 4), criterion = "A")
plot_dispersion(u, design_A, tt = 0, FUN = poly3, theta = rep(0, 4), criterion = "D")

plot_dispersion(u, design_D, tt = 0, FUN = poly3, theta = rep(0, 4), criterion = "A")
plot_dispersion(u, design_D, tt = 0, FUN = poly3, theta = rep(0, 4), criterion = "D")

```

plot_weight

Plot the weight distribution of the optimal design for univaraite regression model

Description

Plot the weight distribution of the optimal design for univaraite regression model

Usage

```
plot_weight(design)
```

Arguments

| | |
|--------|--|
| design | The resulted design that contains the design points and the associated weights |
|--------|--|

Details

This functions produce a figure that contains the location and their associated weights of the resulted optimal design measures.

Value

The plot that shows the given optimal design

Examples

```
Des = list(location = c(-1, +1), weight = c(0.5, 0.5))
plot_weight(Des)
```

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