

# Package ‘trackopt’

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**Type** Package

**Title** Track Numerical Optimization

**Version** 0.1.0

**Description** Tracks parameter value, gradient, and Hessian at each iteration of numerical optimizers. Useful for analyzing optimization progress, diagnosing issues, and studying convergence behavior.

**License** GPL (>= 3)

**Encoding** UTF-8

**RoxygenNote** 7.3.2

**Imports** checkmate, cli, ggplot2, oeli (>= 0.7.2), optimizeR (>= 1.2.0), stats, tibble, utils

**Suggests** testthat (>= 3.0.0)

**Depends** R (>= 4.1.0)

**Config/testthat.edition** 3

**URL** <https://github.com/loelschlaeger/trackopt>

**BugReports** <https://github.com/loelschlaeger/trackopt/issues>

**NeedsCompilation** no

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**Repository** CRAN

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<code>nlm_track</code>	<i>Track numerical optimization</i>
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### Description

- `nlm_track()`: track `nlm` iterations
- `optim_track()`: track `optim` iterations
- `summary()`: summary of optimization track
- `autoplot()`: visualization of optimization for one or two parameters

### Usage

```

nlm_track(
  f,
  p,
  target = NULL,
  npar = NULL,
  gradient = NULL,
  hessian = NULL,
  ...,
  iterations_max = 100,
  tolerance = 1e-06,
  typsize = rep(1, length(p)),
  fscale = 1,
  ndigit = 12,
  stepmax = max(1000 * sqrt(sum((p/typsize)^2)), 1000),
  steptol = 1e-06,
  minimize = TRUE,
  verbose = FALSE
)

optim_track(
  f,
  p,
  target = NULL,
  npar = NULL,
  gradient = NULL,
  ...,
  iterations_max = 100,
  tolerance = 1e-06,
  lower = NULL,
  upper = NULL,
  method = c("Nelder-Mead", "BFGS", "CG", "L-BFGS-B", "SANN", "Brent"),
  control = list(),
  minimize = TRUE,
  verbose = FALSE
)

```

```
)
## S3 method for class 'trackopt'
summary(object, ...)

## S3 method for class 'trackopt'
autoplot(object, iteration = NULL, xlim = NULL, xlim2 = NULL, ...)
```

**Arguments**

<b>f</b>	[function]
	A function to be optimized, returning a single numeric value.
	The first argument of f should be a numeric of the same length as p, optionally followed by any other arguments specified by the ... argument.
	If f is to be optimized over an argument other than the first, or more than one argument, this has to be specified via the target argument.
<b>p</b>	[numeric()]
	The starting parameter values for the target argument(s).
<b>target</b>	[character()   NULL]
	The name(s) of the argument(s) over which f gets optimized.
	This can only be numeric arguments.
	Can be NULL (default), then it is the first argument of f.
<b>npar</b>	[integer()]
	The length(s) of the target argument(s).
	Must be specified if more than two target arguments are specified via the target argument.
	Can be NULL if there is only one target argument, in which case npar is set to be length(p).
<b>gradient</b>	[function   NULL]
	Optionally a function that returns the gradient of f.
	The function call of gradient must be identical to f.
<b>hessian</b>	[function   NULL]
	Optionally a function that returns the Hessian of f.
	The function call of hessian must be identical to f.
<b>...</b>	Additional arguments to be passed to f (and gradient, hessian if specified).
<b>iterations_max</b>	[integer(1)]
	The maximum number of iterations before termination.
<b>tolerance</b>	[numeric(1)]
	The minimum allowed absolute change in function value between two iterations before termination.
<b>typsize, fscale, ndigit, stepmax, steptol</b>	Arguments passed on to <a href="#">nlm</a> .
<b>minimize</b>	[logical(1)]
	Minimize?

<code>verbose</code>	<code>[logical(1)]</code> Print progress?
<code>lower, upper</code>	<code>[numeric()   NULL]</code> Optionally lower and upper parameter bounds.
<code>method, control</code>	Arguments passed on to <code>optim</code> . Elements <code>trace</code> and <code>maxit</code> are ignored in <code>control</code> .
<code>object</code>	<code>[trackopt]</code> A <code>trackopt</code> object.
<code>iteration</code>	<code>[integer(1)]</code> The iteration to plot. If <code>NULL</code> , the last iteration is plotted. This option is useful for creating animations, see <a href="https://bookdown.org/yihui/rmarkdown-cookbook/animation.html#ref-R-animation">https://bookdown.org/yihui/rmarkdown-cookbook/animation.html#ref-R-animation</a> .
<code>xlim, xlim2</code>	<code>[numeric(2)]</code> Ranges for the first and second parameter to plot. If <code>NULL</code> , they are derived from the parameter ranges in <code>object</code> .

### Value

A tibble with iterations in rows.

### Examples

```

himmelblau <- function(x) (x[1]^2 + x[2] - 11)^2 + (x[1] + x[2]^2 - 7)^2
track <- nlm_track(f = himmelblau, p = c(0, 0))
summary(track)
ggplot2::autoplot(track)

```

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